**IEEE P802.15**

**Wireless Personal Area Networks**

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| Project | IEEE P802.15 Working Group for Wireless Personal Area Networks (WPANs) |
| Title | **Proposed Resolution Draft 1.0 comments CID – 1251, 138, 1377, 1319, 273, 274, 1258** |
| Date Submitted | January 2025 |
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| Re: |   |
| Abstract |  |
| Purpose | To propose resolution for comments related to Sensing CIDs – 1251, 138, 1377, 1319, 273, 274, 1258 for “P802.15.4ab™ Draft 1.0 Standard for Low-Rate Wireless Networks” .  |
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Rev 0: Initial version.

***Comment Indices in 15-24-0371-34-04ab-consolidated-comments-draft-1-0 related to sensing:***

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| --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- |
| **Name** | **Index #** | **Category** | **Page** | **Sub-clause** | **Line #** | **Comment** | **Proposed Change** | **Must Be Satisfied?** | **Disposition Status (Accepted, Rejected, Revised)** | **Disposition Detail** |
| Billy Verso | **1251** | **Technical** | **148** | 10.39.6.1 | 10 | Should the term "speed" be used rather than velocity, just to avoid people thinking it is a vector with a direction?  | Change velocity to speed. |  | Revised | Propose to change “velocity” to “radial velocity” at suggested line and related figure for which description applies to. |
| Rojan Chitrakar | **138** | **Technical** | **159** | 10.39.6.6 | **3** | When EOL field is zero, how is the target list continued in a subsequent frame, is the target list the only content of the next report, or are the preceding control fields also present? Details are missing. Also which target list, full or short? | Add detail of the procedure used to continue the target list in the next report when the EOL field is zero. Details are missing. Also specify if the target list is full or short? |  | TBD | TBD |
| Pooria Pakrooh | **1377** | **Technical** | **159** | 10.39.6.6 | **20** | Unclear what the definition of "Rotation" and "Elevation" fields are | Clarify the defenition and range of values |  | TBD | TBD |
| Pablo Corbalán Pelegrín | **1319** | **Technical** | **160** | 10.39.6.6 | **17** | Shouldn't the Elevation angle range from -90º to 90º instead of -180º to 180º? If we do make this change, the resolution for Azimuth and Elevation angles will be different. | Change "-pi to +pi radians" to "-pi/2 to +pi/2 radians". |  | Accepted | Changed as per proposed change |
| Li-Hsiang Sun | **273** | **Technical** | **161** | 10.39.6.6 | **1** | what is the reference for Delay field? i.e. what 0 means? What is the unit? | Please clarify |  | Accepted | Units for Delay is Seconds. Added to text. |
| Li-Hsiang Sun | **274** | **Technical** | **161** | 10.39.6.6 | **3** | what is the unit of the velocity? | Please clarify |  | Accepted | Updated text. Units for Velocity would be seconds/seconds and hence dimensionless. |
| Billy Verso | **1258** | **Technical** | **161** | 10.39.6.6 | **3** | "Velocity field reports the velocity of the target (4 bits, signed integer, zero padded to an octet)"…. Units are missing. Also maybe could uses whole octet as a singed integer, and/or sign extend it rather than zero padding, for easier use. | Specify units. Make full octet signed value. (and change name to "Speed" instead of velocity as it is not a velocity vector.  |  | Revised | Name changed from velocity to radial velocity at suggested line and related figure.Units are explained in description. Would like to keep it a 4 bit signed value.  |

**Discussion for 273, 274:**

Why do we have a Range-Doppler representation as Delay and Velocity with units as in D01?

It is important to understand that 802.15.4ab should be able to serve both mono-static and multi-static sensing.

Much of the literature is on mono-static sensing, and in that case the conversion from delay to range is straightforward (i.e., multiply by speed of light and divide by two). This approach typically does not work for multi-static sensing. In multi-static sensing, the transmitter and receiver are typically not co-located, and the target may be away from the direct line between the two nodes. Therefore, the distance to the line of sight (and/or the angles to the line of sight) needs to be taken into account when calculating range from delay. The accuracy of this kind of conversion may depend on the accuracy with which the radio nodes can localize each other.

In 15.4ab, we are taking the approach that the delay-to-range conversion may not be possible locally, and therefore we transmit the delay information as-is, with the unit [seconds]. The velocity is also on the basis of delay, so instead of [meters]/[seconds], this is expressed in [seconds]/[seconds], meaning this value is dimensionless.

**Discussion for 1251, 1258:**

Billy: CID 1251 proposed changing “velocity” to “speed” which was “accepted” in 15-24-0660r1. However, “velocity” appears 15 times in the sensing clause, so I am thinking about changing them all to “speed”. Please can you take a look and advise me on this.

CID 1258, not resolved yet, which is asking for “velocity” to be changed to “speed” but also looking for the units to be specified. And, as I look at the line in question I see it saying it is a signed value which is confusing since a negative speed does not make sense to me, (while a signed value does not convey a vector direction).

Pooria: I think even though the estimated target speed/velocity is not a vector; it can still take negative values. For example, in monostatic sensing, if the target is getting closer/farther to the sensing device, the radial velocity would be negative/positive, respectively. I am not sure how exactly that goes in bistatic case, which is the topic of this discussion in 4ab.

Frank: We are talking about a radial projection of a velocity, so it can be either positive or negative.

Regarding velocity vs. speed, I believe we are in a sort-of gray area. Typically, “speed” is meant to describe an absolute value, and “velocity” typically has a unit vector specified or implied. Our quantity conforms to neither – in fact, I believe it conforms to the definition of “speed” even less than to the definition of “velocity”. We could sidestep this whole discussion by calling it “projected radial rate of motion”.

Billy: Okay to call it “radial velocity”

**For Comment 273, 274, 1251, 1258:**

**Text changes:** Highlighted in Yellow

**10.39.6.1**

**Change at page 148, Figure 155**

|  |  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- | --- |
| **Bits: 0** | **1** | **2** | **3**  | **4**  | **5**  | **6**  | **7**  |
| Angle of Arrival (Azimuth) | Angle of Arrival (Elevation) | Delay | Radial Velocity | RSSI | Span | Span Reference | Receiver Orientation |

**Change at page 148, Figure 156**

|  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- |
| **Bits: 0–51** | **2-3** | **4-13**  | **14-15** | **16-17** | **18-24** | **25** | **26** | **27** | **28**  | **29**  | **30**  | **31**  | **32**  | **33-39** | **Octets:****0/4/8/16/32** |
| CBW | Bitmap | Bitmap Offset | Reference Tap | Length | Mode dependent Parameter | Angle of Arrival (Azimuth) | Angle of Arrival (Elevation) | Delay | Radial Velocity | RSSI | Span | Span Reference | Receiver Orientation | Reserved | Bitmap |

**Change at Page 148, line 10**

The Radial velocity field value when one means that a radial velocity report is requested, and a value of zero means that

this is not requested.

**10.39.6.6**

**Change at page 158, Line 24:**

The Processed Target Feature Report IE enables the exchange of a processed report for sensing independently of the CIR report. The Processed Target Feature Report IE enables exchange of parameter values for AOA, angle span, delay, delay span, radial velocity, RSSI and receiver orientation. The Processed Target Feature Report IE shall be formatted as shown in Figure 172.

**Change at Page 159, Line 9:**

The Number of Sparse Targets field is an unsigned integer indicating the number of targets for which only a sparse target report is available. A sparse target report contains only delay and Radial velocity information

**Change at Page 160, Figure 173:**

|  |  |  |  |  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- |
| **Bits: 0-5** | **6-13** | **14-15** | **Octets: 0/1**  | **0/1**  | **0/1**  | **0/1** | **0/1**  | **0/1** | **0/1** | **0/1** |
| Target ID | FullTargetReportPresenceBitmap | Reserved | Azimuth | Elevation | Delay | Delay Span | Radial Velocity | RSSI  | Angle Span (Azimuth) | Angle Span (Elevation) |

**Change at Page 160, Figure 174:**

|  |  |  |  |
| --- | --- | --- | --- |
| **Bits: 0-5** | **6-7** | **Octets: 0/1** | **0/1**  |
| Target ID | Sparse Target Report Presence Bitmap | Delay | Radial Velocity |

**Change at Page 160, Figure 175:**

|  |  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- | --- |
| **Bits:1** | **1** | **1** | **1** | **1** | **1** | **1** | **1** |
| AzimuthfieldPresent | ElevationfieldPresent | DelayfieldPresent | DelaySpan fieldPresent | Radial VelocityfieldPresent | RSSIfieldPresent | Angle Span(Azimuth)field Present | Angle Span(Elevation)field Present |

**Change at Page 160, Figure 176:**

|  |  |
| --- | --- |
| **Bits: 1** | **1** |
| Delay fieldPresent | Radial Velocity field present |

**Change at Page 161, Line 1:**

The Delay field gives the delay of a target in the units of Seconds, with line of sight transmission between transmitter and receiver as reference. This is an 8-bit unsigned integer. A delay value is sent for each

target in both full and sparse target lists.

**Change at Page 161, Line 3:**

The Radial Velocity field reports the velocity of the target (4 bits, signed integer, zero padded to an octet). A

Radial velocity value is sent for each target identified. The Radial velocity is on the basis of delay, so, this is expressed in [seconds]/[seconds], meaning this value is dimensionless.

**For Comment 1319:**

**Text changes:** Highlighted in Yellow

**10.39.6.6**

**Change at Page 160, line 17**

The Elevation field value gives the elevation-of-arrival of the target. This is a 7-bit signed value linearly representing an angle from –π/2 to +π/2 radians. Optionally, one Elevation field is sent for each target in the full target list.