IEEE P802.15

Wireless Personal Area Networks

Project	IEEE P802.15 Working Group for Wireless Personal Area Networks (WPANs)	
Title	Kookmin PHY 6 modes: 2D-sequential color code for ISC	
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Re:		
Abstract	This document gives text detail of 2D-sequential color code (a new color code for Image Sensor Communications).	
Purpose	Text input to draft D0.	
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1.0 PHY 6 Layer Operating mode(s)

Optical Camera Communications is introducing three new operating modes.

- PHY 4 accommodates Rolling/Global Shutter Cameras and Low Rate PD
- PHY 5 accommodates Rolling Shutter Cameras
- PHY 6 accommodates 2 Dimensional Screen Codes

PHY 6 Operating Modes				
Modulation	Tx Symbol rate	Rx Frame rate	FEC	Data Rate ⁽⁵⁾
2D-sequential code	5/10	Rx(fps) ≥ 2.Tx ⁽¹⁾	Inner FEC code ⁽²⁾ Outer code ⁽³⁾	(symbol rate) x (#_data LEDs)
4 color 2D-sequential code			Inner FEC code ⁽²⁾ Outer code ⁽³⁾	(symbol rate) x 2.(#_data LEDs)
8 color 2D-sequential code			Inner FEC code ⁽²⁾ Outer code ⁽³⁾	(symbol rate) x 3.(#_data LEDs)
QR-ISC code			level (L) ⁽⁴⁾	R _{QR code} - (some data for clock transmission) ⁽⁵⁾

¹ <u>Oversampling condition</u>: The sampling rate of camera (fps) must be no less than the symbol rate of transmission. For a rolling shutter camera, the oversampling condition is tight compared to a global shutter camera in order to remove any rolling effected image. For a global shutter camera, the frame rate is no less than the symbol rate of transmission.

² <u>inner FEC code (TBD)</u>: Spatial Error Correction Coding to reduce BER.

³ <u>outer code (TBD)</u>: Due to rolling effect, when the frame rate of camera drops to less than a condition of oversampling, a missed data frame needs an outer code at FCS to be corrected.

⁴ Error correction level: the lowest level of error correction (level L) is recommended to accelerate the processing time per image.

⁵ <u>QR-ISC data</u>: Same as QR code. However, some data is shared for clock transmission (i.e. asynchronous bits) to help a receiver decoding asynchronously.

2.0 PHY 6 specifications

2.1 Reference Architecture



clock information (of a data packet/symbol): The information represents the state of a symbol clocked out. The clock information is transmitted along with a symbol to help a receiver in identifying an arrival state of new symbol under presence of frame rate variation.

Symbol clock out —		Clock information bit = 1	Clock information bit = 0	
		symbol į	symbol (i+1)	

2.2 Transmitter Design

Transmitter Design:



A design of 16x16 LEDs transmitter

- □ <u>Reference LEDs</u> (4 LEDs at 4 corners):
 - Transmit *clock information* to help a varying-frame rate receiver in performing *asynchronous decoding*
 - To mitigate the *rolling shutter effect*
- □ 4 Surrounding lines (high gradient difference):
 - To help a receiver in detecting and extracting LEDs in real-time

2.3 Encoder

A proposed 2D-sequential color coc

Reference LEDs	Red channel	Clock infor. bits (0 1 0 1)	
		data bit "0"	data bit "1"
Data LEDs	Red channel	0	1
	Greem channel	0	1
	Blue channel	0	1

8-colors encoding true table

3 bits-Input	Color-Output
000	Black
100	Red
010	Green
001	Blue
110	Yellow
101	Magenta
011	Cyan
111	White



An integration of sequential data into a QR-code interface



QR-ISC Tag is color modulation in Image Sensor Communications (ISC) integrated into QR code. The ISC uses three channels of Red, Green and Blue to transmit data, along with that is the **asynchronous symbols** to support **varying-frame-rate** camera receivers.

- We borrow the format and error correction from QR code standard.
- An asynchronous bits Inserted is need in helping a varying-frame-rate receiver decoding asynchronously.

2.4 Error Correction



- A spatial Error Correction Coding is need as an inner code
- Outer code is helpful in correcting any error caused by frame rate drop.

3.0 PHY 6 Layer Decoding Method (for Kookmin color code)

3.1 Perspective Distortion Mitigation



LEDs extraction matrix using line detection under perspective distortion

Step 1: 4-Edges detection using image processing

- Edges are detected by using Hough transform
- The position of 4 corners and matrix positions of LEDs

$$A_i(w,h) = e_i \cap e_{i+1}; with \quad i = \overline{1, 4}; \ e_5 \equiv e_1.$$

$$P_n(w,h) = e_p \cap e_q; with \quad p,q = \overline{1, 16}; \ n = \overline{1, 256}$$

Step 2: 16x16 LED-positions Matrix forming

- Input: 4-corner positions A_i(w, h)
- Output: 16x16 matrix of LED-positions

3.2 Rotation Mitigation





- A blue channel is applied to transmit a signal that allows a receiver in identifying presence of rotation.
- At any time, a state of a reference LED is always different from the other three. The rotation is identified easily by checking those four states of reference LEDs.

3.3 Rolling Effect Detection and Cancellation

$$M^{k} = \begin{bmatrix} s_{11}^{k} & s_{12}^{k} \\ s_{21}^{k} & s_{22}^{k} \end{bmatrix}$$

A state-Matrix of 4 reference LEDs at the sample #k:
(Notice that the reference signals of those LEDs are transmitted at red channel)

Detect the rolling effect in an image:

- If $(M^k != 0 \& M^k != 1)$ then (the image has rolling effect)



Notice: The detection is still true under rotation!

3.4 Asynchronous Decoding

This scheme is for helping a receiver in decoding under presence of frame rate variation.



When at least one sample is captured on an interval of a symbol, a majority voting is applied
Clock information bit is helpful to identify the group of samples for a symbol voting.