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Abstract: [This contribution describes revision of TSV model for LOS desktop channel environments.]

**Purpose:** [Contribution to mmW TG3c meeting.]

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# Revision of TSV model for LOS desktop channel environments

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# Agenda

- Revision of TSV model
- Extracted TSV model parameters
- Proposal of default antenna for simulation
- Path-loss results for desktop environment

#### Modification of TSV model TSV model = Statistical two-path model + S-V model $h(t) = \beta \,\delta(t) + \sum_{l=0}^{L-1} \sum_{m=0}^{M_l-1} \alpha_{l,m} \,\delta(t - T_l - \tau_{l,m}) \,\delta(\varphi - \Psi_l - \psi_{l,m})$ Refer to appendix A for each parameter Statistical two-path response (LOS desktop.) Fixed impulse response (LOS office, residential...etc) Relative power $\overline{\beta}$ Rician factor ( $\Delta K$ ) Small Rician factor for each cluster ( $\Delta k$ ) $\sqrt{\Omega_0}$ S-V model response $\Gamma, \Lambda, \gamma, \lambda$ Time of Arrival

- Each cluster has the  $\Delta k$  of Small Rician factor
- Effects of the receiver antenna pattern are considered in  $\alpha_{1,m}$



Fig1. Extraction of parameter γ

Fig2. Impulse response of each cluster

Giving the Small Rician factor ( $\Delta k$ ) is more suitable to express the cluster in the model. (Doc. 06/302)

# Extracted TSV model parameters

	TSV	Small	S-V model oriented parameters							Number
	Model	Rician								of cluster
		factor								
Parameter	$\Omega_0(D)$	k	Γ	$1/\Lambda$	γ	$1/\lambda$	$\sigma_1$	$\sigma_2$	$\sigma_{\phi}$	Ν
	[dB]	(Δk)	[ns]	[ns]	[ns]	[ns]	cluster	ray	[deg]	
Tx:30	4.44 D-	2.53	21.1	27.0	8.85	1.56	3.01	7.69	34.6	3
Rx:30	105.4	(11.0 dB)								
Tx:60	3.46 D-	3.97	22.3	21.1	17.2	2.68	7.27	4.42	38.1	3
Rx:60	98.4	(17.2 dB)								

#### Channel model for LOS desktop environment is available

Refer to appendix B and C for each parameter

# Antenna pattern effect

TSV model CIR:  $h(t) = \beta \,\delta(t) + \sum_{l=0}^{L-1} \sum_{m=0}^{M_l-1} \alpha_{l,m} \,\delta(t - T_l - \tau_{l,m}) \,\delta(\varphi - \Psi_l - \psi_{l,m})$ 

$$\left|\alpha_{l,m}\right|^{2} = \Omega_{0} e^{-T_{l}/\Gamma} e^{-\tau_{l,m}/\gamma - \Delta k \left[1 - \delta(m)\right]} \sqrt{G_{r}(0, \Psi_{l} + \psi_{l,m})} \angle \alpha_{l,m} \propto \text{Uniform}[0, 2\pi)$$

### Rx antenna gain in horizontal plane is included

# Default antenna patterns

Antenna gain:  $G_r(\theta, \phi) = GD(\theta, \phi)$ 

- Omni directional antenna:  $D(0, \phi) = 1$
- Directional antenna:

$$D(0,\phi) = \exp(-\alpha \phi^2)$$

Simple Gaussian distribution can be used



### Path loss model for LOS desktop environment

Path loss [dB] =  $PL_0 + 10n \log_{10}(\mu_D / D_0)$ 



• Path loss at D<sub>0</sub>=1m distance

$$PL_0[dB] = 20\log_{10}\left(\frac{4\pi D_0}{\lambda}\right) \approx 68.4$$

 $\lambda \approx 4.8 \mathrm{mm} \, (f = 62.5 \, \mathrm{GHz})$ 

Path loss exponent

*n* = 2.03

## • Path loss of LOS component follows free space loss

## <u>Summary</u>

- TSV-model was revised
- Parameters for LOS desktop environment were extracted based on the TSV-model
- Path loss for LOS desktop environment was measured
- LOS desktop channel model based on TSV-model is now available
- Default antenna patterns are proposed to simplify the simulation

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### Appendix A: Definition of TSV model (revised)

$$\begin{aligned} \mathbf{CIRP:} \quad h(t) &= \beta \ \delta(t) + \sum_{l=0}^{L-1} \sum_{m=0}^{M_{l-1}} \alpha_{l,m} \ \delta(t - T_l - \tau_{l,m}) \ \delta(\varphi - \Psi_l - \Psi_{l,m}) \\ (\text{Complex impulse response} \\ \hline \left[\alpha_{i,n}\right]^2 &= \Omega_0 e^{-T_l/\Gamma} e^{-\tau_{i,m}/\gamma - k[1 - \delta(m)]} \sqrt{G_r(0, \Psi_l + \Psi_{l,m})}, \ \angle \alpha_{i,m} \propto \text{Uniform}[0, 2\pi) \\ \hline \left[\alpha_{i,m}\right]^2 &= \Omega_0 e^{-T_l/\Gamma} e^{-\tau_{i,m}/\gamma - k[1 - \delta(m)]} \sqrt{G_r(0, \Psi_l + \Psi_{l,m})}, \ \angle \alpha_{i,m} \propto \text{Uniform}[0, 2\pi) \\ \hline \mathbf{Two-path response} \\ &= \sqrt{PL} \left(\frac{\mu_D}{D}\right)^2 \left| \sqrt{G_n G_{r,1}} + \sqrt{G_{r_2} G_{r_2} \Gamma_0} \exp\left[j \frac{2\pi}{2\mu_i h_2} \frac{2\mu_i h_2}{D}\right] \right| \\ P(T_l | T_{l,1}) = \Lambda \exp[-\Lambda(T_l - T_{l,1})] \ l > 0 \\ p(\tau_l | T_{l,1}) = \Lambda \exp[-\Lambda(T_l - \tau_{l,1})] \ l > 0 \\ p(\tau_l | T_{l,1}) = \Lambda \exp[-\Lambda(T_l - \tau_{l,1})] \ m > 0 \\ \hline \mathbf{Two-path response} \\ = \sqrt{PL} \left(\frac{\mu_D}{D}\right)^2 \left| \sqrt{G_n G_{r,1}} + \sqrt{G_{r_2} G_{r_2} \Gamma_0} \exp\left[j \frac{2\pi}{2\mu_i h_2} \frac{2\mu_i h_2}{D}\right] \right| \\ Path number of G_{ij} and G_{ij}(1: direct, 2: refrect) \\ \hline \mathbf{Two-path parameters} (\mathbf{4}) \\ D \propto \text{Uniform: Bistance between Tx and Rx} \\ h_{j} \simeq \text{Uniform: Height of Tx} \\ h_{j} \simeq \text{Variage of distance between Tx and Rx} \\ \Gamma_0 | \approx \text{Refection coefficient} \\ |\Gamma_0| \approx 1: \text{LOS Desktop environment} \\ (incident angle = \pi/2) \\ |\Gamma_0| \approx 0: \text{Other LOS environment} \\ (incident angle = \pi/2) \\ |\Gamma_0| \approx 0: \text{Other LOS environment} \\ (incident angle = \pi/2) \\ |\Gamma_0| \approx 0: \text{Other LOS environment} \\ (incident angle = \pi/2) \\ |\Gamma_0| \approx 0: \text{Other LOS environment} \\ (incident angle = \pi/2) \\ |\Gamma_0| \approx 0: \text{Other LOS environment} \\ (incident angle = \pi/2) \\ |\Gamma_0| \approx 0: \text{Other LOS environment} \\ (incident angle = \pi/2) \\ |\Gamma_0| \approx 0: \text{Other LOS environment} \\ (incident angle = \pi/2) \\ |\Gamma_0| \approx 0: \text{Other LOS environment} \\ (incident angle = \pi/2) \\ |\Gamma_0| \approx 0: \text{Other LOS environment} \\ (incident angle = \pi/2) \\ |\Gamma_0| \approx 0: \text{Other LOS environment} \\ (incident angle = \pi/2) \\ |\Gamma_0| \approx 0: \text{Other LOS environment} \\ (incident angle = \pi/2) \\ |\Gamma_0| \approx 0: \text{Other LOS environment} \\ (incident angle = \pi/2) \\ |\Gamma_0| \approx 0: \text{Other LOS environment} \\ (incident angle = \pi/2) \\ |\Gamma_0| \approx 0: \text{Other LOS environment} \\ (incident angle = \pi/2) \\ |\Gamma_0| \approx 0: \text{Ot$$

 $|\Gamma_0| \cong 0$ : Other LOS environment

(Laplace distribution)

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Appendix C: Averaged power of the first ray of S-V response



- $\Omega_0$  increases due to distance, because directional antenna is used in transmitter
- Conventional S-V model does not consider this effect