

Project: IEEE 802.11bb Task Group

Submission Title: IEEE 802.11bb Reference Channel Models for Vehicular Communications

Date Submitted: July 06, 2018

Source: Murat Uysal (Ozyegin University), Farshad Miramirkhani (Ozyegin University), Tuncer Baykas (Istanbul Medipol University), Emrah Kinav (Ford Otosan), and Omer Rustu Ergen (Ford Otosan).

Address: Ozyegin University, Nisanteppe Mh. Orman Sk. No:34-36 Çekmekoy 34794 Istanbul, Turkey

Voice: +90 (216) 5649329, Fax: +90 (216) 5649450, E-Mail: murat.uysal@ozyegin.edu.tr

Abstract: This contribution proposes LiFi reference channel models for vehicular communications.

Purpose: To introduce reference channel models for the evaluation of different PHY proposals.

Notice: This document has been prepared to assist the IEEE 802.11. It is offered as a basis for discussion and is not binding on the contributing individual(s) or organization(s). The material in this document is subject to change in form and content after further study. The contributor(s) reserve(s) the right to add, amend or withdraw material contained herein.

Release: The contributor acknowledges and accepts that this contribution becomes the property of IEEE and may be made publicly available by 802.11.

IEEE 802.11bb

Reference Channel Models for Vehicular Communications

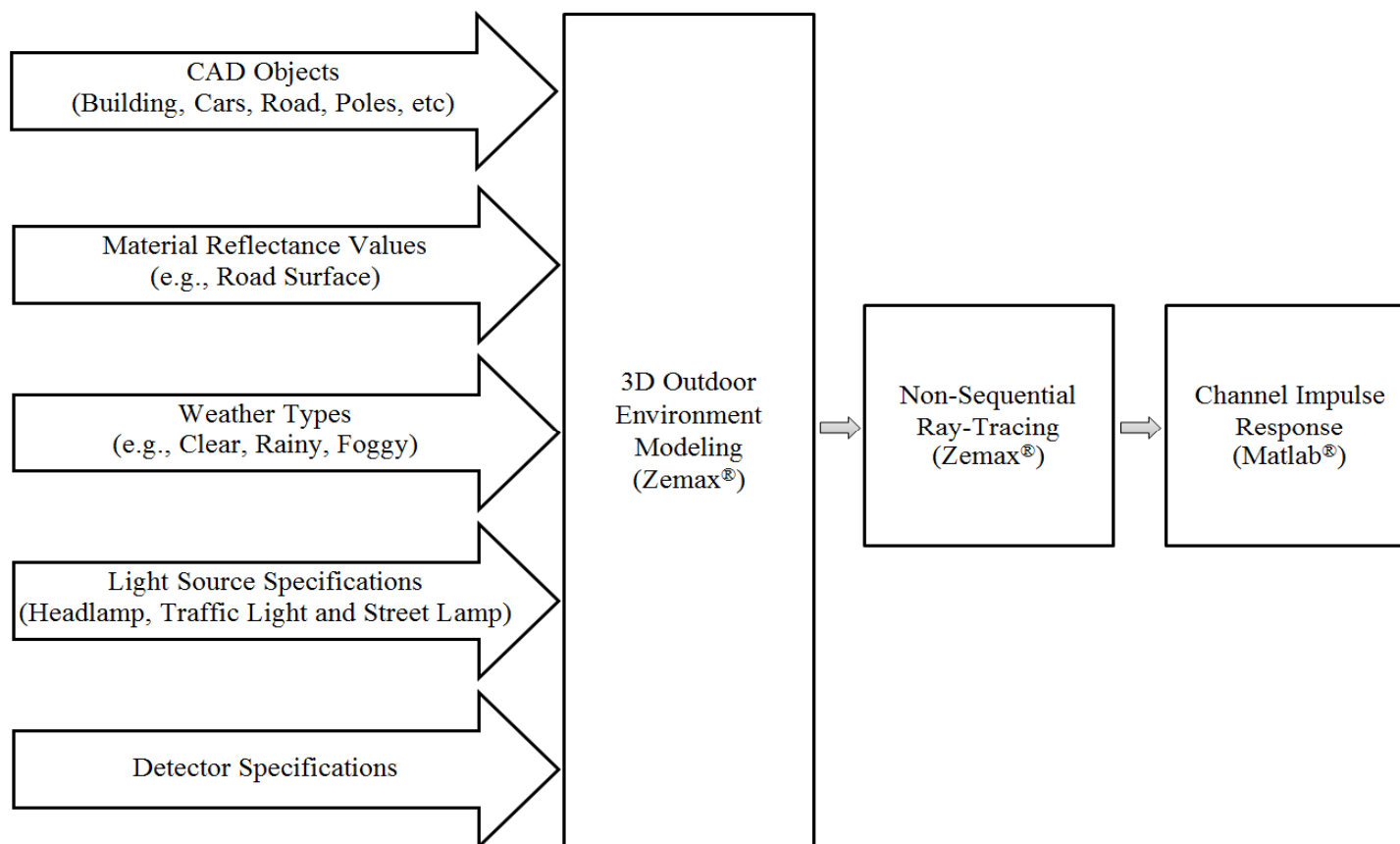
Outline

- Introduction
 - Overview of Channel Modeling Methodology
 - Modeling of the Outdoor Environment
 - Headlamp Modeling
 - Modeling of Weather Conditions (Clear Weather, Rainy Weather and Foggy Weather)

- Vehicular Scenario under Consideration
 - Channel Impulse Responses (CIRs)
 - Effective Channel Responses
 - Channel Characteristics

- Conclusions

Overview of Channel Modeling Methodology^[1]



[1] M. Elamassie, M. Karbalayghareh, F. Miramirkhani, R. C. Kizilirmak, and M. Uysal, "Effect of fog and rain on the performance of vehicular visible light communications," *IEEE 87th Vehicular Technology Conference (VTC2018-Spring)*, Porto, Portugal, Jun. 2018.

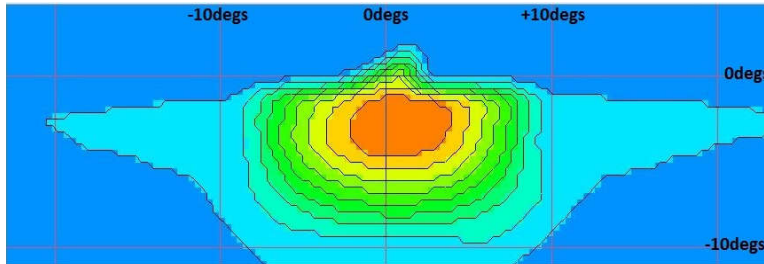
Modeling of the Outdoor Environment

- Creation of 3D outdoor environment in Zemax[®] involves the selection of
 - Dimension and shape of the outdoor environment
 - CAD objects within the environment (buildings, cars, roads etc)
 - Position and type of transmitters and receivers
 - Type and properties of materials

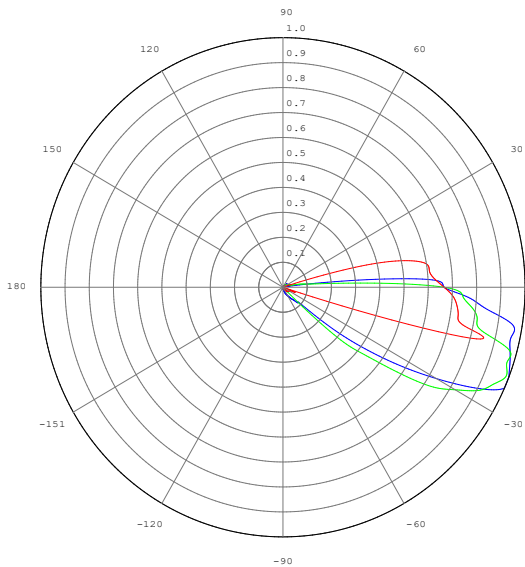
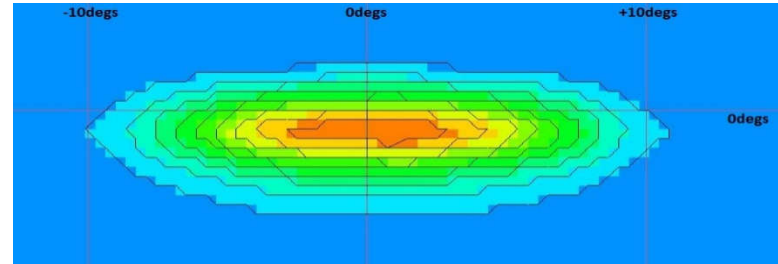
Class	Road Surface Composition	Mode of Reflectance
R1	Asphalt with aggregate including a minimum of 15% artificial brightener aggregate	Mostly diffuse
R2	Asphalt with aggregate including a minimum of 60% gravel sized larger than 10 mm Asphalt with aggregate including a minimum of 10-15% artificial brightener aggregate	Mixed diffuse and specular
R3	Asphalt with dark aggregate-the surface becomes rough after several months of use	Slightly specular
R4	Very smooth asphalt	Mostly specular

Headlamp Modeling

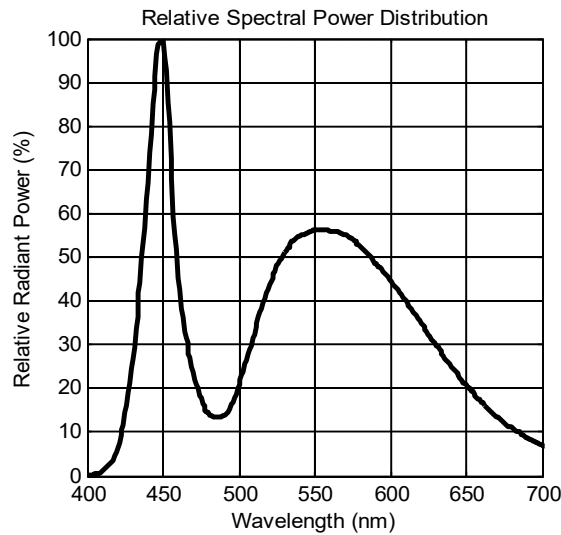
Spatial distribution of low-beam headlamp



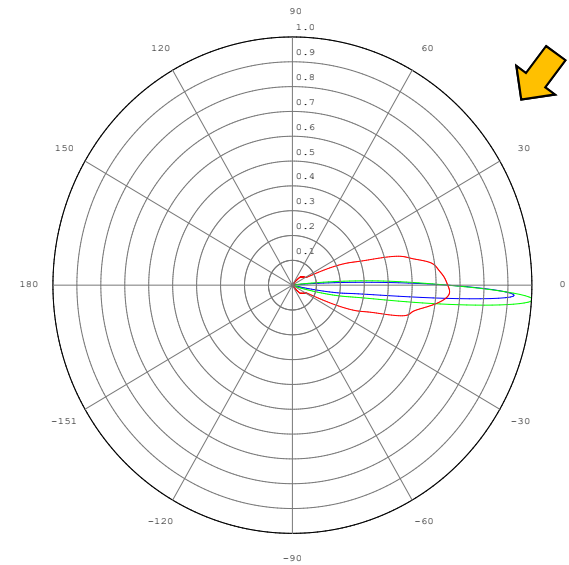
Spatial distribution of high-beam headlamp



Relative intensity distributions of low-beam headlamp



Relative spectral power distribution of Philips LUXEON Rebel



Relative intensity distributions of high-beam headlamp



Modeling of Weather Conditions

- To model the interaction of rays with the air, Mie scattering is used to model rainy and foggy weather conditions with different visibilities.
- “Bulk scatter” method in the Zemax software allows providing the input parameters
 - “Particle index” (the refractive index of particles)
 - “Size” (the radius of the spherical particles)
 - “Density” (the density of particles). The characteristics of various weather types are listed in Table below.

	Particle Index	Size (μm)	Density (cm^{-3})
Clear	1.000277	10^{-4}	10^{19}
Rain	1.33	100	0.1
Fog, $V = 50 \text{ m}$	1.33	10	124.6
Fog, $V = 10 \text{ m}$	1.33	10	622.6

Channel Impulse Response (CIR)

- Based on Monte Carlo Ray Tracing.
- Sobol sampling is used for speeding up ray tracing.
- The Zemax[®] non-sequential ray-tracing tool generates an output file, which includes all the data about rays such as the detected power and path lengths for each ray.
- The data from Zemax[®] output file is imported to MATLAB[®] and using these information, the multipath CIR is expressed as

$$h(t) = \sum_{i=1}^{N_r} P_i \delta(t - \tau_i)$$

P_i = the power of the i^{th} ray

τ_i = the propagation time of the i^{th} ray

$\delta(t)$ = the Dirac delta function

N_r = the number of rays received at the detector

Effect of LED Response

- In addition to the multipath propagation environment, the low-pass characteristics of the LED sources should be further taken into account in channel modelling.

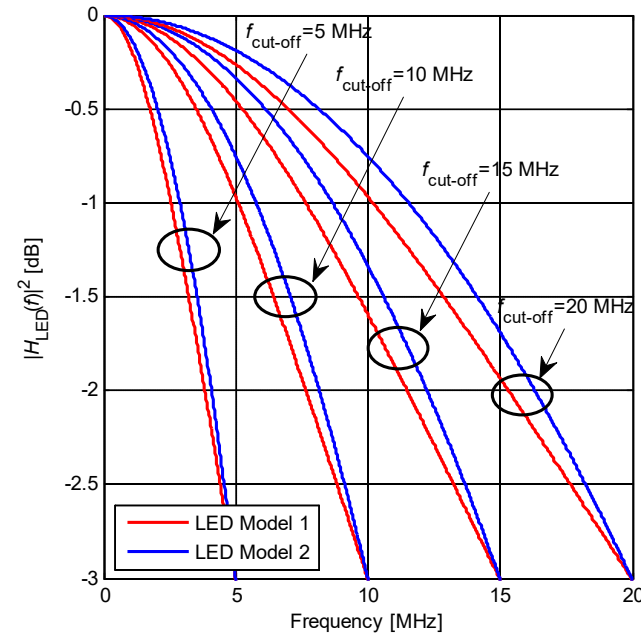
LED Model 1 [2]

$$H_{\text{LED}}(f) = \frac{1}{1 + j \frac{f}{f_{\text{cut-off}}}}$$

LED Model 2 [3]

$$H_{\text{LED}}(f) = e^{-\ln(\sqrt{2}) \left(\frac{f}{f_{\text{cut-off}}} \right)^2}$$

$f_{\text{cut-off}}$: 3 dB cut-off frequency of the LED

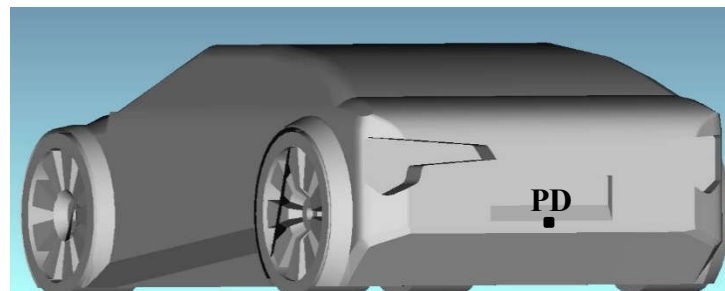
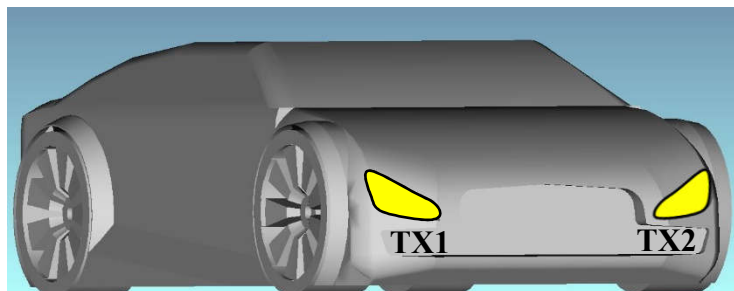
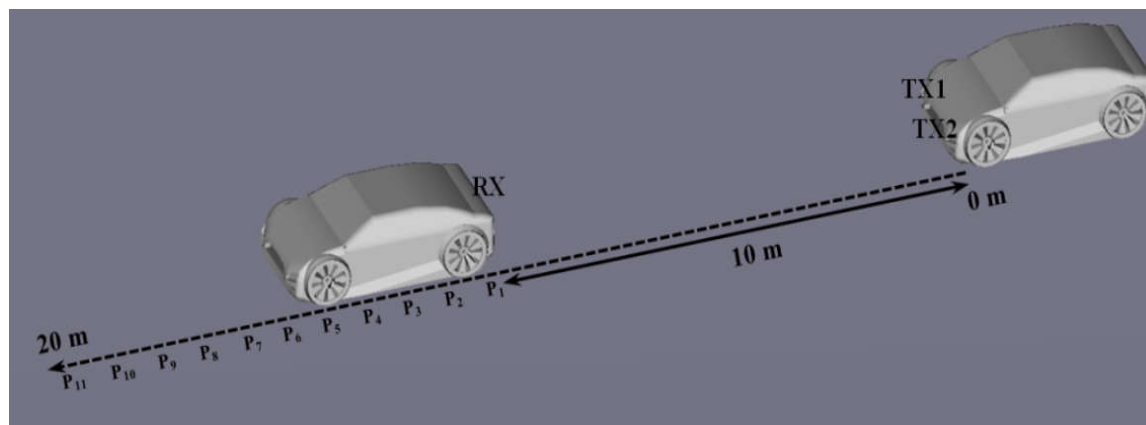


[2] L. Grobe, and K. D. Langer, “Block-based PAM with frequency domain equalization in visible light communications,” In *IEEE Globecom Workshops (GC Wkshps)*, pp. 1070-1075, 2013.

[3] M. Wolf, S. A. Cheema, M. Haardt, and L. Grobe, “On the performance of block transmission schemes in optical channels with a Gaussian profile,” In *16th International Conference on Transparent Optical Networks (ICTON)*, pp. 1-8, 2014.

Simulation Scenario

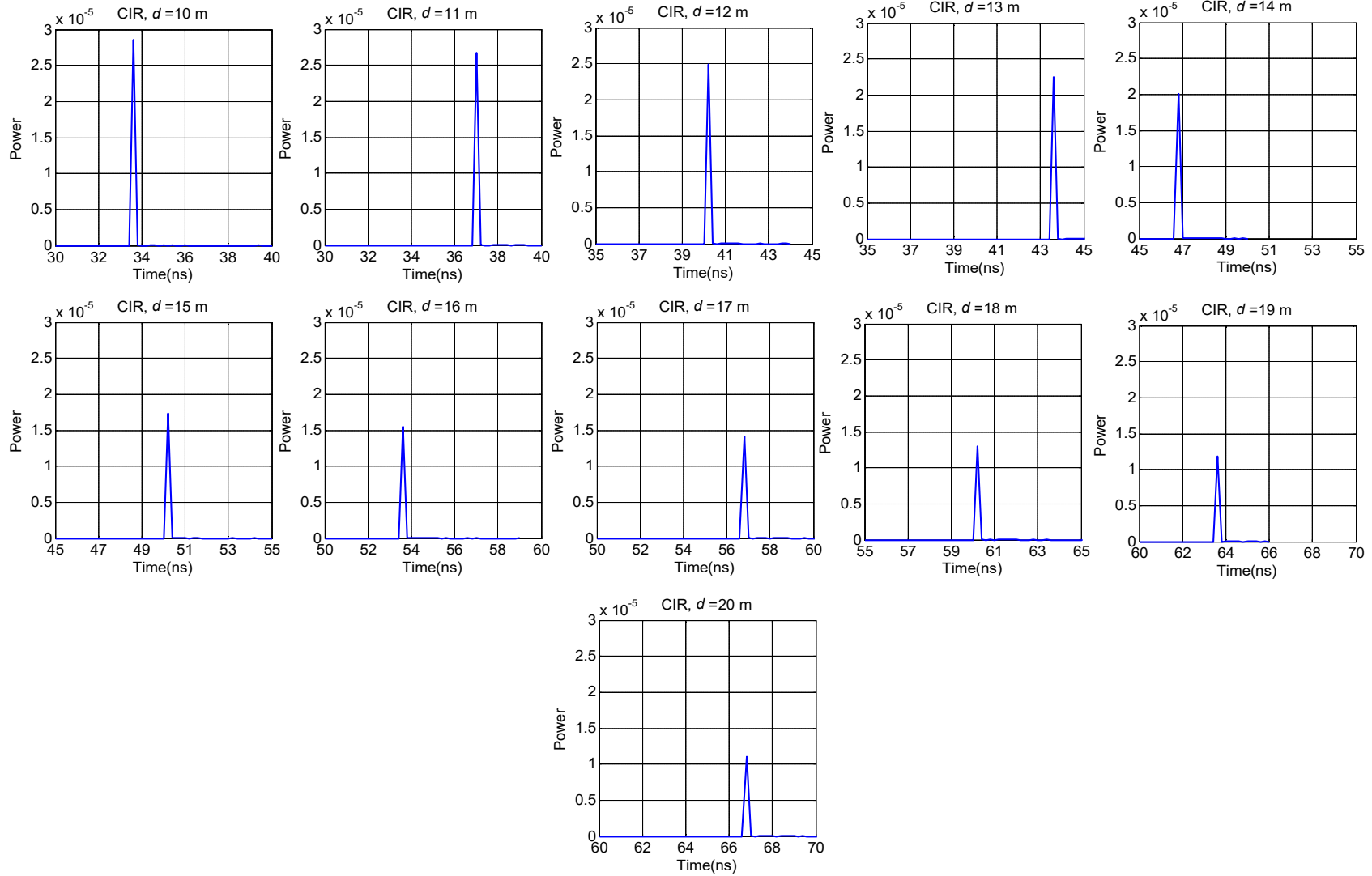
- We assume that the two vehicles are separated from each other initially at a distance of 10 meter.



Simulation Parameters

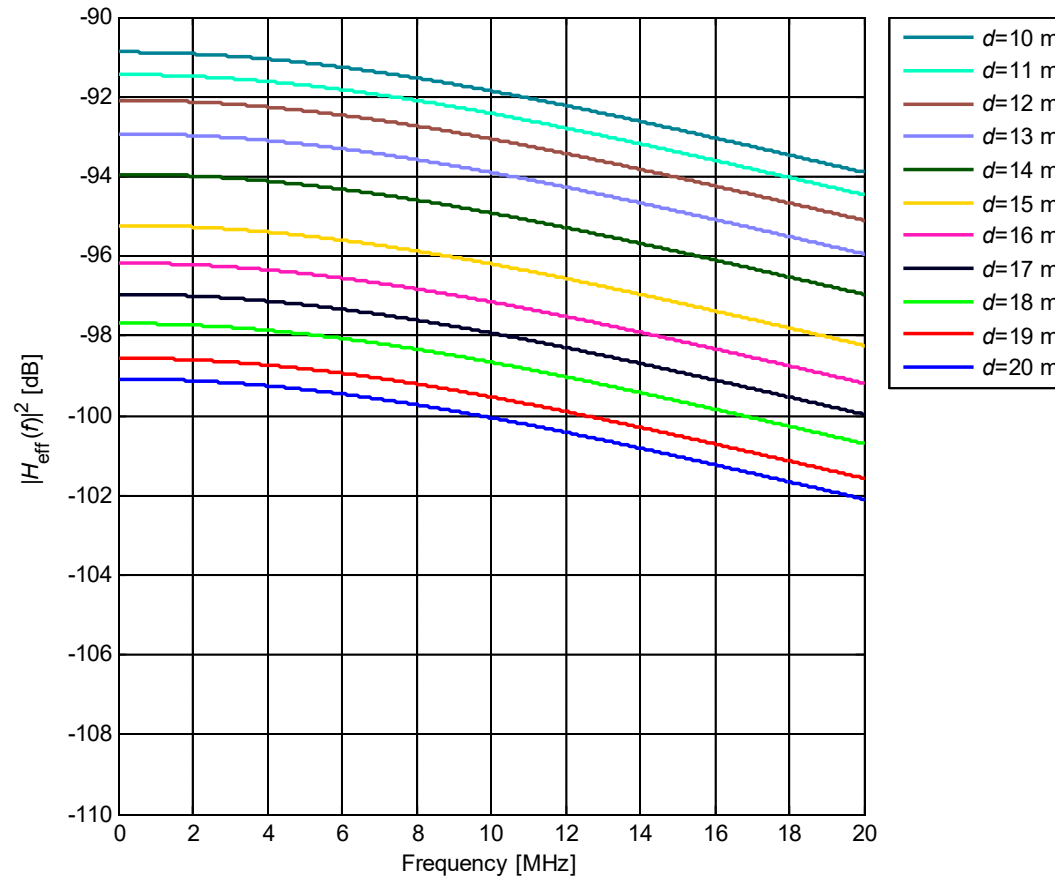
Transmitter specifications	Type: High-beam headlamp Brand: Philips Luxeon Rebel white LED Power: 1 Watt per each headlamp
Receiver specifications	Area: 1 cm ² FOV: 180°
Coating material of vehicle	Black gloss paint
Road type	R2
Weather types	Clear Rainy Foggy with visibilities of $V = 50$ m and 10 m

CIR Results (Clear Weather)

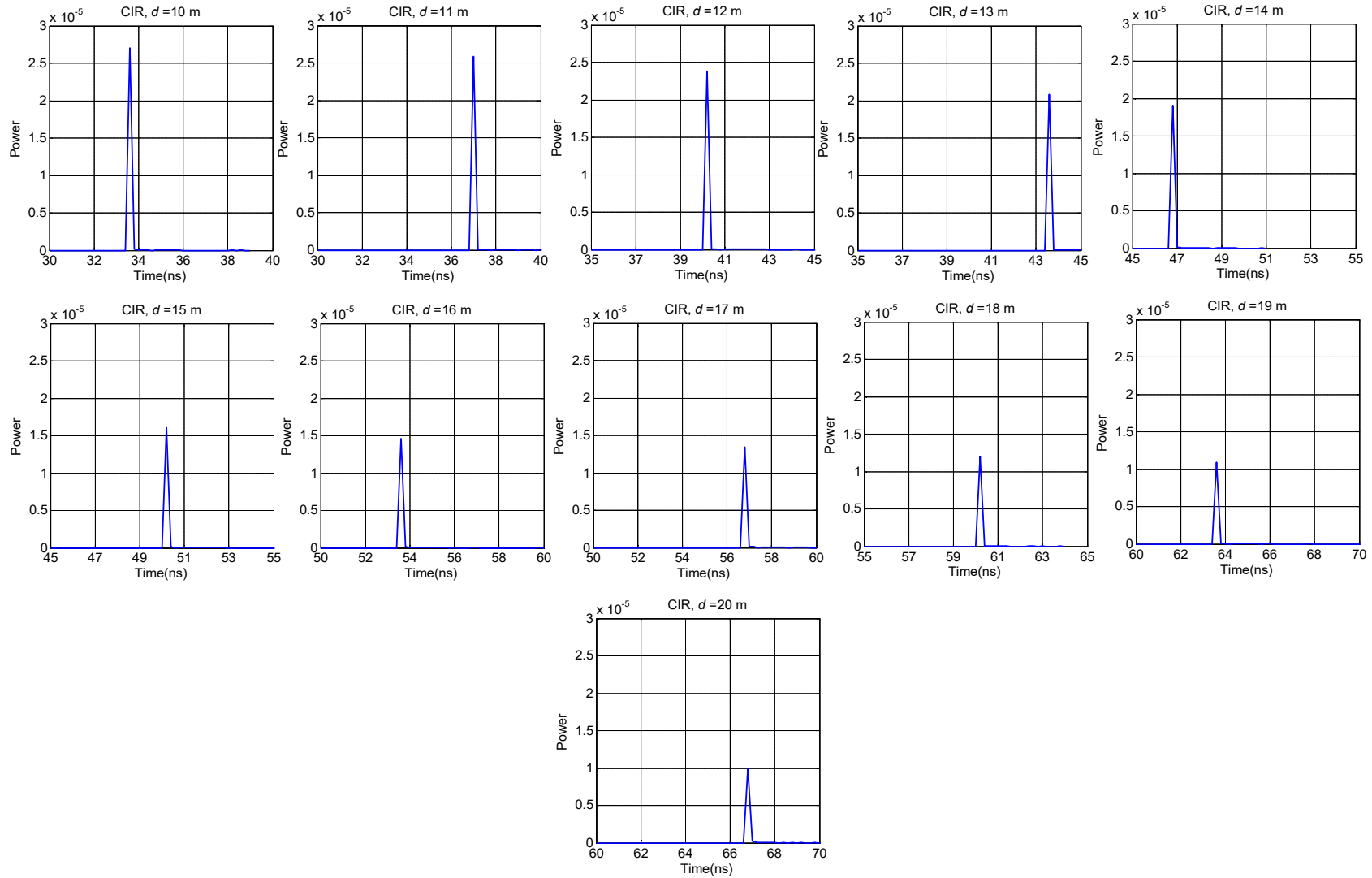


Effective Channel Responses (Clear Weather)

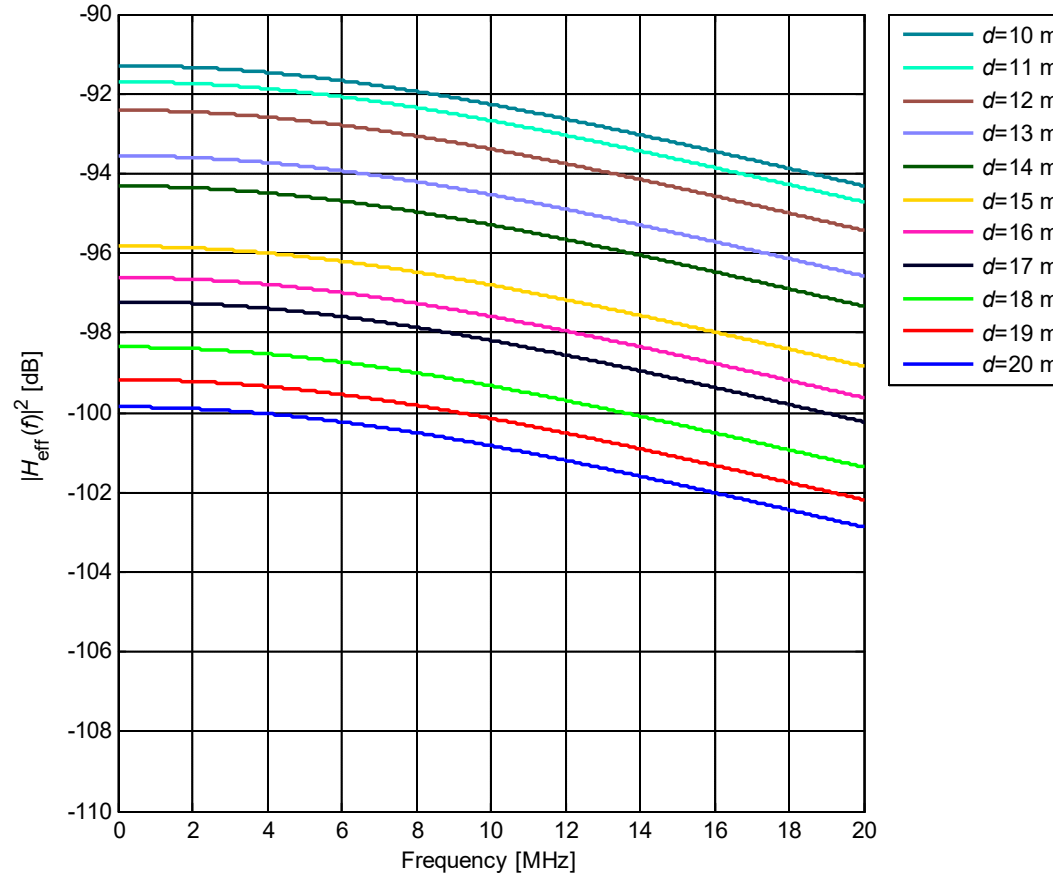
- For the effective channel responses, the “LED Model 1” with cut-off frequency of 20 MHz is considered.



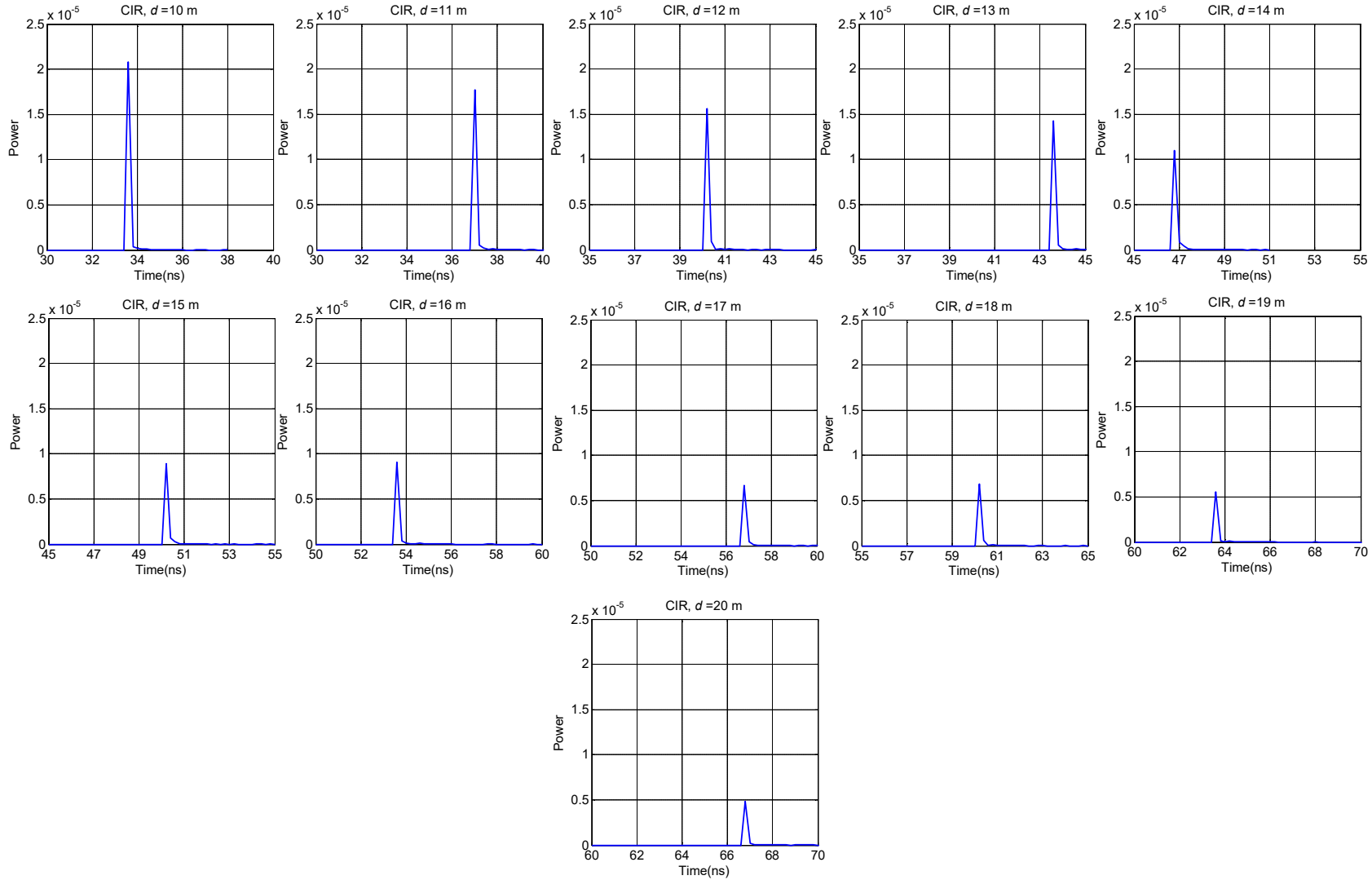
CIR Results (Rainy Weather)



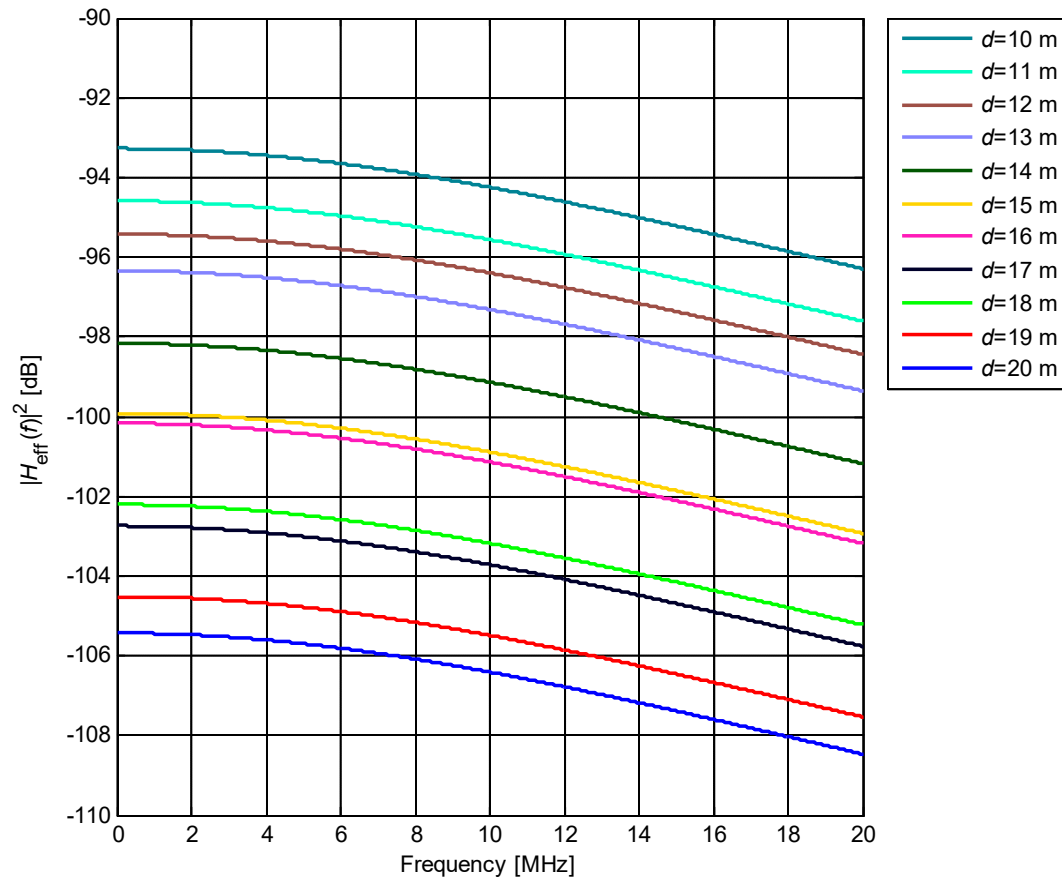
Effective Channel Responses (Rainy Weather)



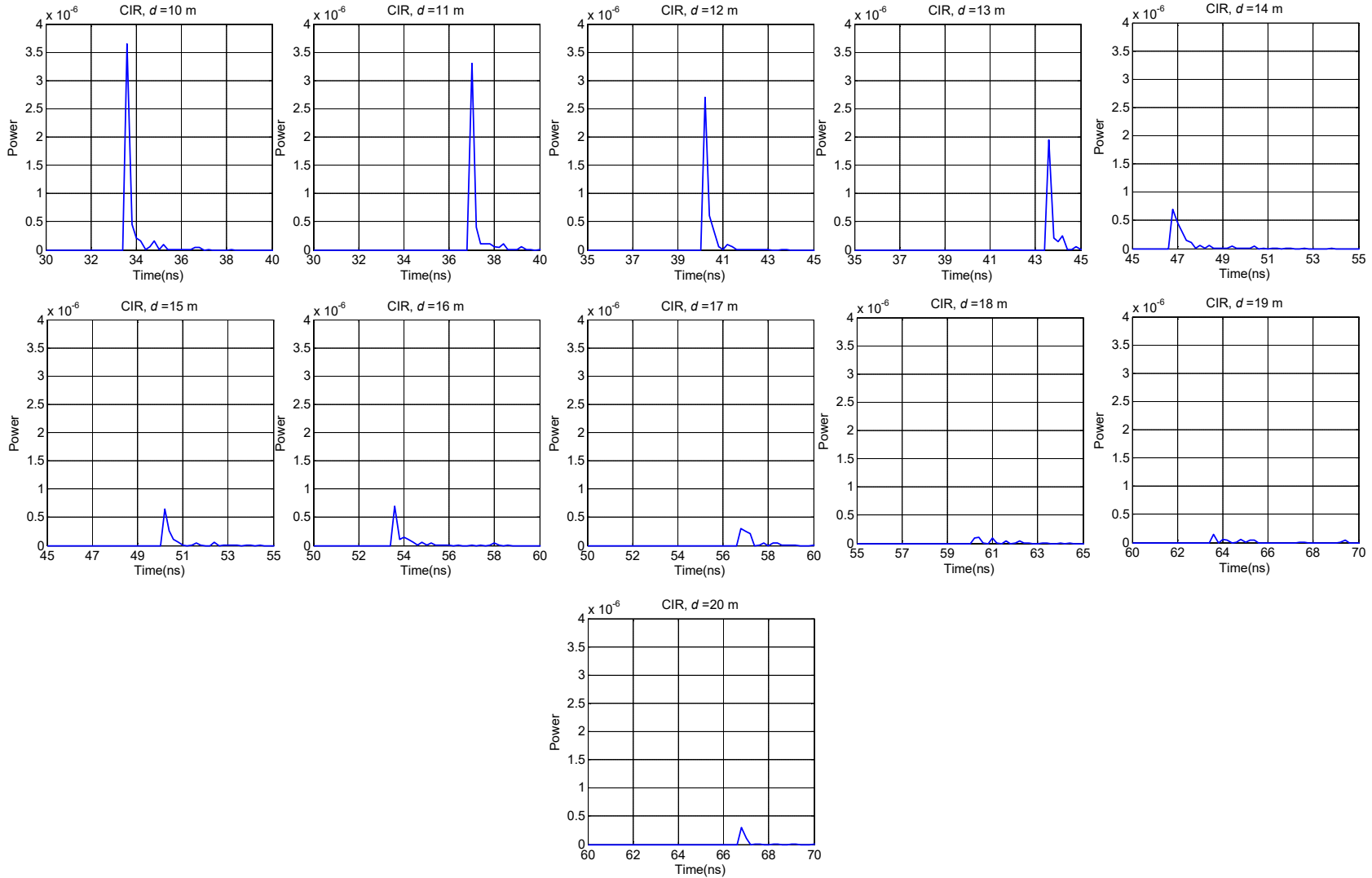
CIR Results (Foggy Weather, $V=50$ m)



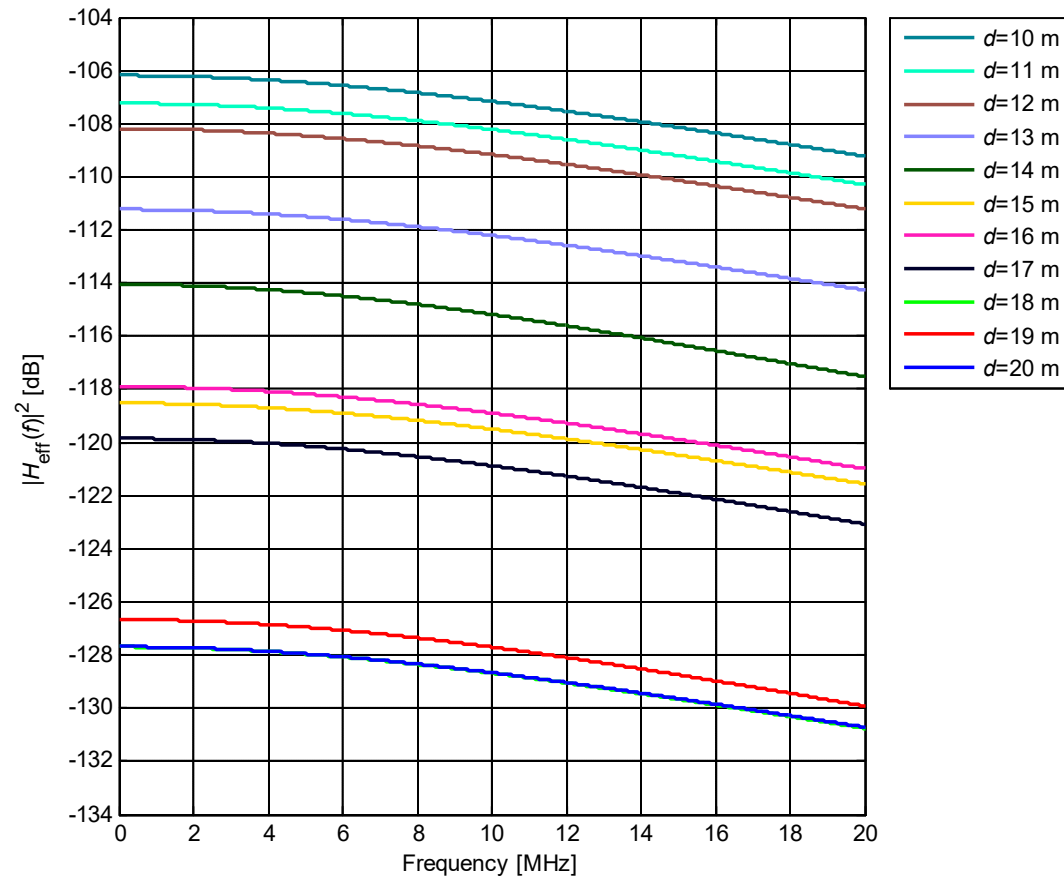
Effective Channel Responses (Foggy Weather, $V=50$ m)



CIR Results (Foggy Weather, $V=10$ m)



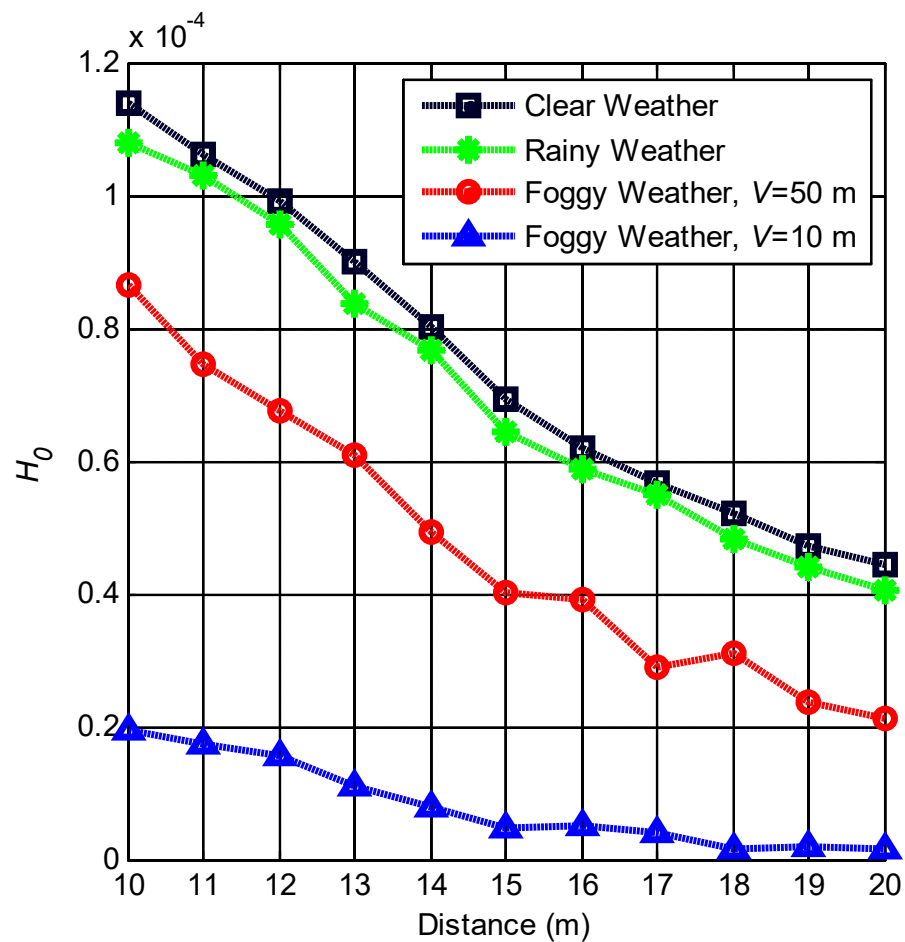
Effective Channel Responses (Foggy Weather, $V=10$ m)



Channel Characteristics (1/2)

d (m)	τ_{RMS} (ns)				H_0			
	Clear	Rain	Fog ($V=50$ m)	Fog ($V=10$ m)	Clear	Rain	Fog ($V=50$ m)	Fog ($V=10$ m)
10	7.95	7.95	7.95	7.97	1.14×10^{-4}	1.08×10^{-4}	8.66×10^{-5}	1.95×10^{-5}
11	7.95	7.95	7.95	7.99	1.06×10^{-4}	1.03×10^{-4}	7.44×10^{-5}	1.73×10^{-5}
12	7.95	7.95	7.95	7.95	9.92×10^{-5}	9.56×10^{-5}	6.76×10^{-5}	1.55×10^{-5}
13	7.95	7.95	7.95	7.97	9.01×10^{-5}	8.38×10^{-5}	6.08×10^{-5}	1.09×10^{-5}
14	7.95	7.95	7.95	8.56	8.01×10^{-5}	7.68×10^{-5}	4.93×10^{-5}	7.91×10^{-6}
15	7.95	7.95	7.95	7.97	6.92×10^{-5}	6.45×10^{-5}	4.03×10^{-5}	4.73×10^{-6}
16	7.95	7.95	7.95	8.02	6.20×10^{-5}	5.89×10^{-5}	3.91×10^{-5}	5.08×10^{-6}
17	7.95	7.95	7.95	8.14	5.66×10^{-5}	5.50×10^{-5}	2.91×10^{-5}	4.06×10^{-6}
18	7.95	7.95	7.95	7.99	5.21×10^{-5}	4.82×10^{-5}	3.09×10^{-5}	1.64×10^{-6}
19	7.95	7.95	7.95	8.16	4.71×10^{-5}	4.39×10^{-5}	2.37×10^{-5}	1.85×10^{-6}
20	7.95	7.95	7.97	7.96	4.43×10^{-5}	4.05×10^{-5}	2.13×10^{-5}	1.64×10^{-6}

Channel Characteristics (2/2)



Conclusions

- This contribution proposes LiFi reference channel models for vehicular communications to assist the IEEE 802.11bb.