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| Project | **Human Factor for Immersive Content**<<http://sites.ieee.org/sagroups-3079/> **>** |
| Title | **The Automatic Calibration Procedure of the Device Coordinates Providing the Projection Mapping Content** |
| DCN | **3079-21-0078-00-0002** |
| Date Submitted | **October 01, 2021** |
| Source(s) | **Sangkwon Peter Jeong** ceo@joyfun.kr **(JoyFun Inc.)****GookHwan Lee** ghlee@joyfun.kr **(JoyFun Inc.)****Jimmy Jang** marketing@joyfun.kr **(JoyFun Inc.)****HyeonWoo Nam** hwnam@dongduk.ac.kr **(Dongduk Women's Univ. )** |
| Re: |  |
| Abstract | This document describes a procedure and a method for the automated calibration between two coordinate systems above. |
| Purpose | The purpose of this document is to이 문서의 목적은 프로젝션 맵핑을 활용한 혼합현실 장치의 좌표계 자동 보정 절차를 표준에 반영하는 것이다. |
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**The Automatic Calibration Procedure of the Device Coordinates Providing the Projection Mapping Content**

1. **Applied Area**

When the relevant content is provided by a mixed reality content providing device using the RGB-D sensor, which is built into the beam projector, and depth camera, the beam projector displays the user interface, and the RGB-D sensor detects the user’s motion.

When installing the mixed reality content providing device, even if the coordinates are corrected manually, the coordinate system may be distorted due to external shock or vibration when using the device. Also, the coordinate system correction of the projection area of the beam projector and the recognition area of the RGB-D sensor should be able to be automatically corrected.

1. **Adjustment Procedure of Coordinate system**

This chapter describes the procedure for adjusting the coordinate system of the RGB-D sensor built into the depth camera and the projection area of the beam projector.

* 1. **Adjustment Environment of Coordinate system**

When the relevant content is provided by a mixed reality content providing device using the RGB-D sensor, which is built into the beam projector, and depth camera, the beam projector displays the user interface, and the RGB-D sensor detects the user’s motion.



(Figure 2-1) Comparison of RGB-D sensor coordinate system and projection area coordinate system

Since the RGB-D sensor built into the beam projector and the depth camera is an independent device, an independent coordinate system exists as shown in the figure above, and related functions must be implemented by mapping these coordinate systems when implementing content.

Since the content development environment and the content operation and installation environment are different, the coordinates must be manually adjusted when installing the device.

Unlike the development environment, the distance between the beam projector and the floor may be different in the installation environment. Also the distance or direction between the RGB-D sensor and the beam projector may be different.

Even if such coordinate correction is manually performed when installing a mixed reality content providing device, this coordinate system may be distorted by external impact or vibrations when using the device.

In order to correct the distortion of the coordinate system, that is, to provide mixed reality content smoothly, the coordinate system adjustment of the projection area of the beam projector and the recognition area of the RGB-D sensor should be automatically performed.

The RGB-D sensor coordinate system and the coordinate system of the beam projector projection area are adjusted by the following procedure.



(Figure 2-2) Adjustment Procedure of Coordinate system

* 1. **Adjustment Procedure**
		1. **Project an image to be recognized using a beam projector**

A beam projector included in the mixed reality content providing device projects an image of a specific color onto the area where the mixed reality content is to be provided.

Repeat the process below while changing this color to another color so that it can be distinguished from the color of the floor.

* + 1. **Image acquisition with RGB sensor**

The image projected by the beam projector is acquired with the RGB sensor (RGB camera) included in the mixed reality content providing device.



(Figure 2-3) Example screen acquired with RGB sensor

* + 1. **Image area Coordinate Recognition**

From the image, which is acquired with RGB sensor, an image region of a specific color is found. And a coordinate information in the image of the region is acquired.



(Figure 2-4) Example screen detecting the area projected by the beam projector

As in the example screen, coordinate information of the four corners of the area projected by the beam projector is acquired.

The coordinate information of the four corners obtained in this way is converted into depth sensor coordinates using a coordinate mapping table between the depth sensor and the RGB sensor.

* + 1. **Coordinate adjustment compared to content reference coordinates**

The coordinates of the RGB-D sensor and the beam projector projection area are corrected by comparing the depth sensor coordinates for the four corners of the area obtained by projecting with the beam projector in the above step with the reference coordinates applied when developing mixed reality content.